Interaction between vehicles and infrastructure (lane markers)

Andreas Lökholm & Carina Björnsson Volvo Cars

Autonomous driving vs manual driving with support

Manual driving: Driver responsible, vehicle supports



Support and assist for safer and less stressful driving

Autonomous Drive: Vehicle is responsible in autonomous mode



Fully autonomous. The vehicle can only deal with clear & defined road environments

Active Safety

Collision avoidance & Driver Support

- Collision avoidance: Warn, brake, or steer at hazardous situation
- Support functions: Parking, support in daily driving

Many dependencies:

Certification, Rating, Consumer tests, etc...









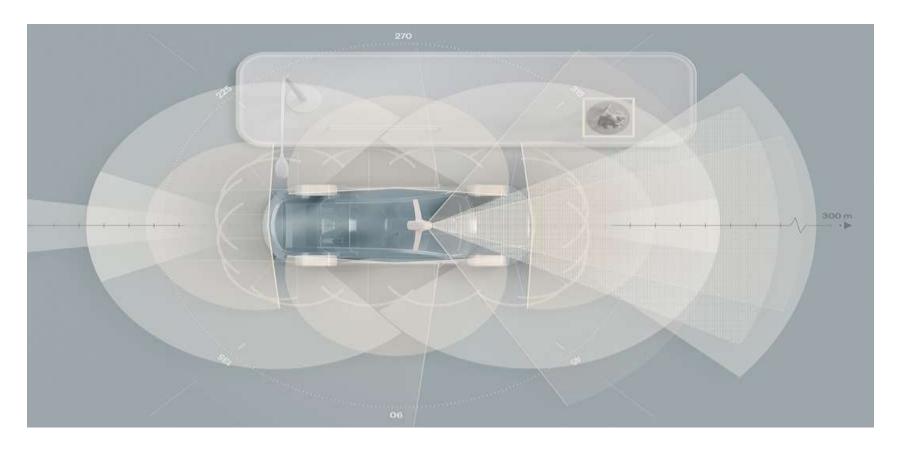




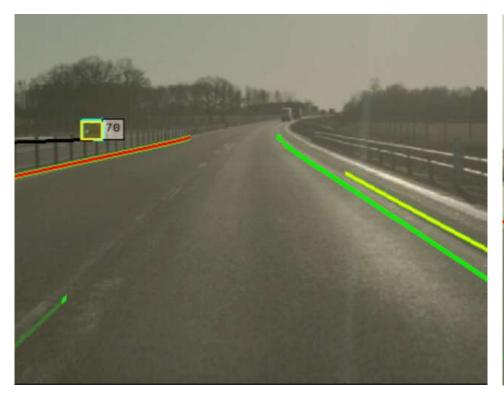


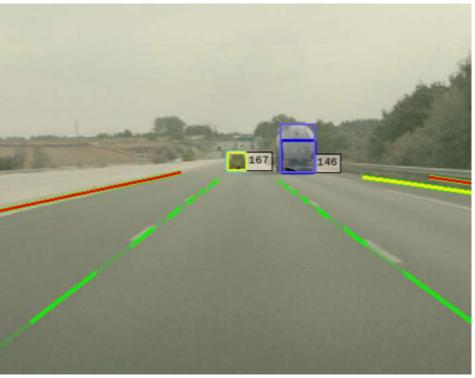


Seeing and interpreting the environment

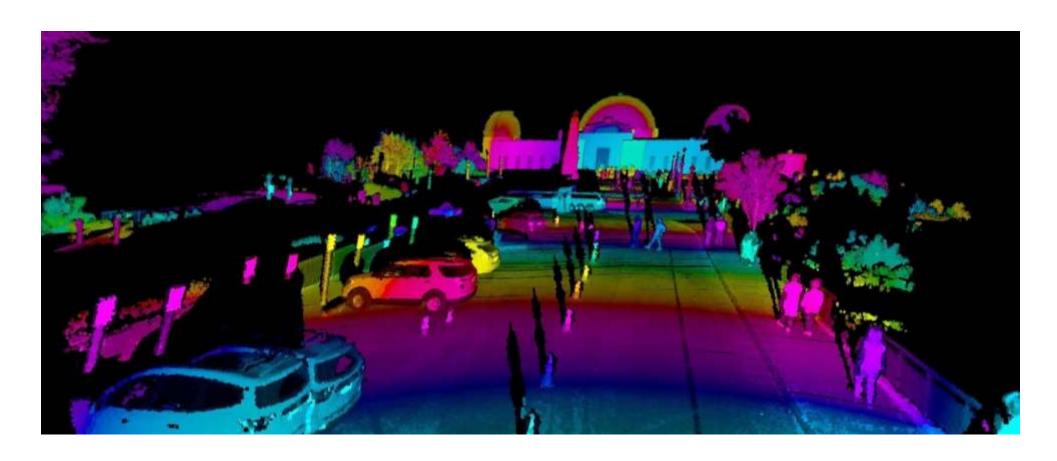


Vehicle's perception of lane markers





Lidar





























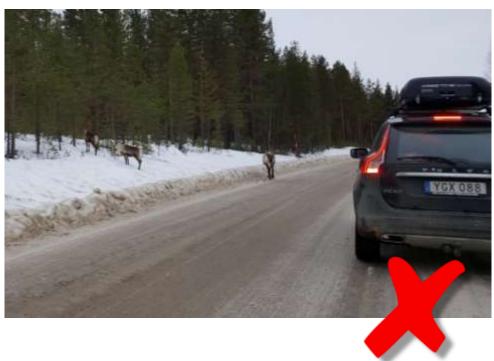






Clear lane markers important for good functionality

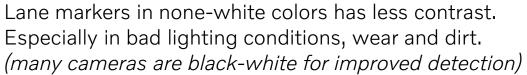




What makes it difficult

- Colours, contrast
- Contamination, dirt, water snow, leaves
- Wear
- Road works, temporary lane markers
- Complexitet, non-standardisation
- To have a good functional performance is good lane visibility and distinct road edges very important



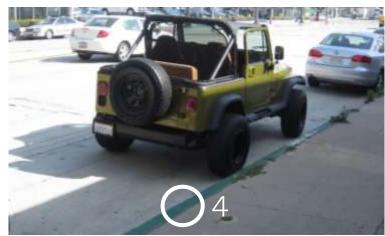


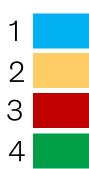






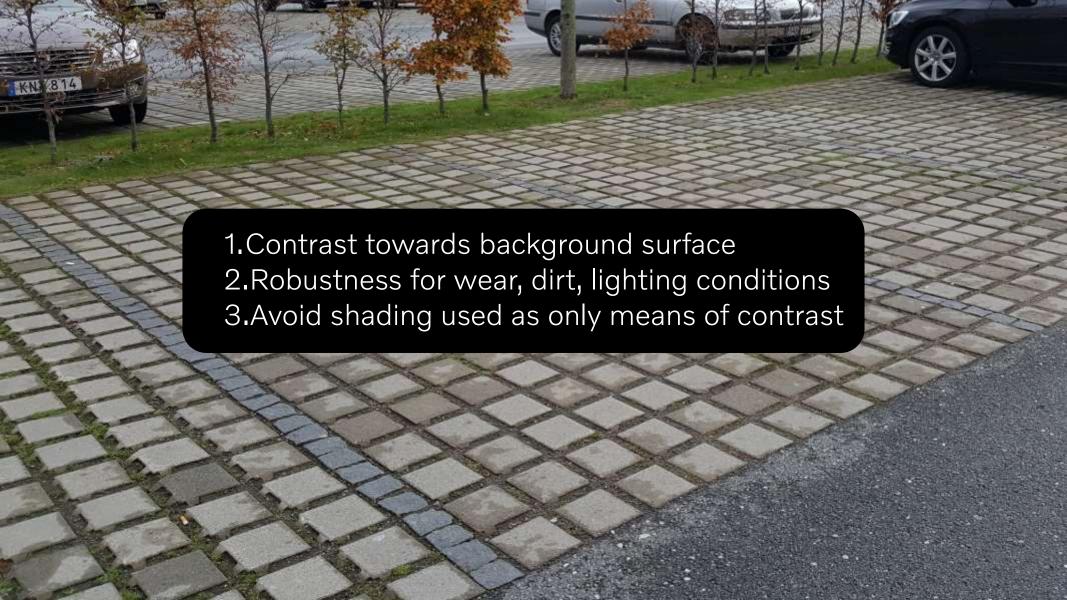












Fleet learning & customer feedback





Fleet learning - Road work



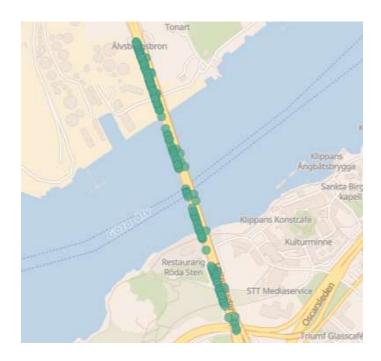






Fleet learning - Road work

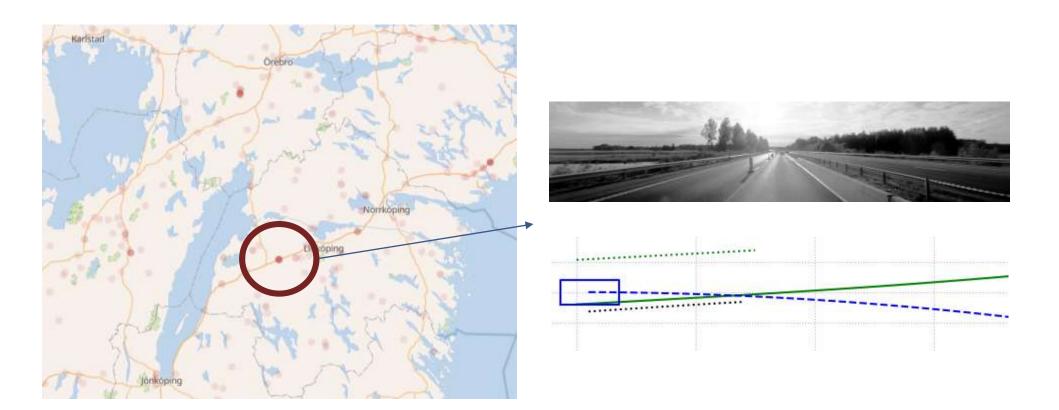
1 month with road work



1 month without road work



Fleet learning - Road work



Fleet learning - Customer feedback



Fleet learning - Different road designs





Conclusion: How to make roads safer

- Straight , clean, highly visible lane markers
- Standardisation
- Important to restore after road work or maintenance, especially the lane
- Future is here: the machines way of seeing things needs consideration

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