

FCTUC DEPARTAMENTO DE ENGENHARIA CIVIL FACULDADE DE CIÊNCIAS E TECNOLOGIA

UNIVERSIDADE DE COIMBRA

# **Roundabouts in Portugal State of the Art**

STOCKHOLM ROUNDABOUT DESIGN AND CAPACITY SEMINAR, 1<sup>ST</sup> JULY

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## Roundabouts in Portugal - State of the Art

### Outline

**Evolution of roundabouts in Portugal** 

#### **Current situation**

- Roundabout types
- Main problems

#### **Previous research**

Speeds and trajectories

#### **Current research**

- Headway distribution models
- Estimation of critical headways
- Pedestrian effect on roundabout capacity

### History of roundabouts in Portugal

- Portugal has the first roundabouts constructed according to the Henard's Principles
- Since the 80's the number of roundabouts has increased exponentially
- The exact number of roundabouts is unknown but there are certainly some thousands.







#### Portugal



#### **Roundabout types**

- Single lane roundabouts a few examples, normally located on rural or residential areas
- Multilane roundabouts the most common in Portugal, namely on urban collectors roads
- Compact roundabouts (with truck aprons) have became popular
- Mini roundabout extremely rare
- Others types (double roundabouts, signalized) – extremely rare



### PORTUGAL

### **Roundabouts in Portugal**

#### **Main Problems**

- We have a Roundabout Design Guide...
  - ... but the document has not yet been published.
- The Road Code doesn't include rules about how to circulate on roundabouts ...

... and there are a lot of contradictory recommendations

 Fortunately, most drivers drive correctly!

#### PROIBIDO Circular na faixa exterior da rotunda, excepto no troço imediatamente anterior à

saída pretendida

#### DIMENSIONAMENTO DE ROTUNDAS



DEZEMBRO 2006



#### Portugal

#### **Main Problems**

Tipical behaviours...





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#### Main problems

geometrical design problems...



excessive number of lanes in the ring



large roundabouts

lack of entry deflection

lack of channelization

traffic signals\

### Portugal

#### Main problems

Obstructions in the central island...





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#### **Driver behavior**

The study was based on 2100 trajectories collected under free flow conditions

#### The instrumented vehicle



- 14 drivers
- 20 circuits per driver in 10 roundabouts

#### DATA COLLECTION VARIABLES:

- drivers' control actions
- dynamic response of the vehicle
- Vehicle position (with IR beacons)





#### Portugal

#### **Speed Profile Analyses**

#### **Speed Dispersion**









Representação das Trajectórias Reais

#### Portugal

#### **Trajectories**





#### **Driver behaviour**

drivers' behavior results from a relative valorization of the "temptation/desire" to minimize driving discomfort and the "obligation" to respect road markings.

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#### **Trajectory Analyses**

#### Real Trajectory Adequacy – Right Lane/Left Lane



- Higher average deviations at the right lane
- Best designs can expect 20% of incorrect trajectories on right lane

### PORTUGAL

#### **Main Conclusions**

#### **Speed and Trajectory Profiles**

- There is a linear and positive correlation between approach speed and entry speed;
- Low trajectory deflections usually results in greater acceptance by drivers in maintaining their circulation lane. However this also results in high entry speeds and big behavioral heterogeneities;
- High deflection levels tend to impose high levels of discomfort which induce drivers to invade adjacent lanes searching for more direct and comfortable trajectories.
- Global results confirm the hypothesis that drivers' behavior results from a relative valorization of the "temptation/desire" to minimize driving discomfort and the "obligation" to respect road markings.
- Some "Lane Invasion" is inevitable even in well designed roundabouts. Global results have shown that adequate drivers' behavior can be expected to be observed at well designed roundabouts.

#### Gap-acceptance models: motivation

Linear regression models are insensible to entry flow distribution and opposing flow distribution



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#### Gap-acceptance models: motivation

Linear regression models are inadequate to study new layouts, particularly when lane-bylane analyses is required. This is particularly important when using the more complex capacity formulas (e.g., Hagring) that are sensible to traffic distribution among entry and circulatory lanes



### **Headway distribution model**



#### Motivation

 The representation of inter-vehicular time intervals in the major stream is one of the building block of gap-acceptance models

#### Simplest approach: the Negative Exponential Distribution

- Only one parameter λ. Easy to estimate.
- Method of moments: λ = q (average flow in the opposing stream)
- Resulting capacity model: Siegloch formula

$$F(t) = 1 - e^{-\lambda t}$$

$$C = \frac{q_M \ e^{-q_M t_c}}{1 - e^{-t_f}}$$

### Headway distribution model

# Limitations of the exponential model

- Allows unrealistic short headways
- Does not describe platooning
- Can be considered realistic for very low/flow conditions only (<150 veh/h)</li>



### Headway distribution model

#### Alternative - Cowan M3 Distribution

- 3 Parameters  $(\phi, \Delta, \lambda)$
- It is assumed that part of the drivers (1 φ) are in platoons with a uniform headway (Δ). The others (φ) are "free" and distributed according to the neg. exponential distribution
- Method of moments:

 $\lambda = \frac{\phi q}{1 - \Delta q}$ 



### Headway distribution model

# Estimation for a given observed distribution

- Using solver in Excel
- The fit is very bad for t< Δ but those intervals would be rejected anyway!



### Headway distribution model

#### Inference of a bunching model motivation:

- In practical application only the traffic flow is know, not the headway distribution
- So, it is necessary to relate Φ or Δ with the opposing flow, q<sub>M</sub>
- A linear relation was assumed and calibrated using a large number of capacity estimates in sites where the headway distribution was known

 $\Phi = 1.55 - 3.11 q_{M}$ 

(for  $q_M > 0.178$  veh/s, with  $\Delta = 2s$ )



### Headway distribution model

#### Application of the calibrated Cowan M<sub>3</sub>

#### parameters to one-lane and two-lane roundabouts

- General capacity formula for *n*-lanes, each having different Cowan M<sub>3</sub> parameters
- Comparison against conventional model ( $\phi = 1, \Delta = 0$ and  $\lambda = q$ , with superimposed arrivals)



Φ =1.55 – 3.11 q

(for q > 0.178 veh/s, with  $\Delta$ =2s)





### Estimation of critical-headway and follow-up times

#### Objectives

- Compare different methods (Raff, Wu, Maximum Likelihood, Siegloch) and obtain calibrated values for portuguese conditions
- Develop a critical-headway model based on microscopic variables

#### Data collection: FHWA methodology

- Opposing traffic: inner + outer lanes

   (even at right lane entries, where there is
   no physical conflict between some
   movements)
- Siegloch method 4s headway threshold used to identify congested periods





■ Raff ■ Wu ■ ML ■ Logit

#### ■ Critical-headway (s) ■ Follow-up time (s)



### **Estimation of critical-headway and follow-up times**

#### Some conclusions

- At two-lane entries, critical headways is usually smaller at the right lane
- Wu's method is the one that provides the closer estimates to the Maximum Likelihood method
- Logit's method indicates that the waiting time decreases the critical headway
- Siegloch's method returns the lowest estimates
- The follow-up time is relatively uniform [2.0 2.5 s]

### **Estimation of critical-headway – microscopic model**

#### **Objectives**

- Obtain critical-headway estimates to be used in analytic capacity models
- Should captures the interactions between the driver/vehicle dynamics and the intersection geometry
- Must be easily implemented in a spreadsheet

#### Methodology

- Based on Gipps' equations to describe vehicle acceleration and car-following behavior
- Parameters calibrated from video recordings





### **Estimation of critical-headway – microscopic model**

#### Calibration

- Screen to World coordinates transformed using the DLT algorithm
- Safety margins and acceleration profiles extracted from video observations



### **Estimation of critical-headway – microscopic model**

#### Validation

Comparison against conventional methods based on observations



### **Pedestrian effect on roundabout capacity**

#### Objectives

- Understand how a crosswalk located in a exit arm affects the roundabout performance (walking distance vs vehicle delays)
- Identify the preferable domain for a pelican crossing instead of a zebra crossing



### **Pedestrian effect on roundabout capacity**

#### Methodology

- The capacity of a roundabout without crosswalks was taken as reference
- Construction of an assessment matrix based on different levels of:
  - Traffic flow
  - Pedestrian flow
  - Crosswalk locations
  - Control type (zebra / pelican crossing)
- Comparative assessment of the different scenarios using a microscopic simulator (Paramics)

### **Pedestrian effect on roundabout capacity**

#### Some conclusions

- The effect of pedestrian crossings fades as the distance between the crosswalk and the exit increases
- When N = 1 (aprox. 5 m), there is a reduction of the roundabout performance, even for low levels of traffic and pedestrians
- N = 3 (aprox. 15 m) seems to be a good starting number
- For extreme congestion levels, the pelican crossings perform better



## References

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# **Thank You**

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